

# Some Takeaways from Poly at Work 2024

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In this document, I describe some takeaways from the Poly at Work 2024 workshop. Developments were heavily impacted by discussions with other participants. The ideas presented here are joint work with Reed Mullanix.

## 1 Indexed Inductive Types via Endobicomodules

In programming languages, it is common to have inductive types. For example, the following type describes syntax trees:

```
type t =
  | Bool of bool
  | String of string
  | And of t * t
  | Concat of t * t
  | IsEmpty of t
  | If of t * t * t
```

This type can be understood as the initial algebra of the polynomial  $p = 2 + S + y^2 + y + y^3$ , where  $S$  is the set of finite-length strings. Via initiality, we can write a map out of this type to evaluate syntax trees. However, we are presented with a problem: what should we do with invalid states, like `Concat (Bool true, String "a")`? To remedy this, we may break `t` into two mutually-inductive types: one for boolean expressions and one for string expressions.

```
type t1 =
  | Bool of bool
  | And of t1 * t1
  | IsEmpty of t2

and t2 =
  | String of string
  | Concat of t2 * t2
  | If of t1 * t2 * t2
```

Now, an element of `t1` is a well-formed boolean expression, and an element of `t2` is a well-formed string expression. Invalid states are no longer representable: `Concat (Bool true, String "a")` is not an element of either `t1` or `t2`. We can express types `t1` and `t2` simultaneously as the

initial algebra of a polynomial in two variables:

$$\begin{aligned} p_1 &= 2 + y_1^2 + y_2 \\ p_2 &= S + y_2^2 + y_1 y_2^2 \end{aligned}$$

Such a polynomial in two variables can be understood as the data of an endobicomodule

$$2y \xleftarrow{p} \triangleleft 2y,$$

using the polynomial  $p$  from the earlier type. This consists of two maps,  $\lambda$  and  $\rho$ , subject to some coherence conditions.

- A left-module  $\lambda : p \rightarrow 2p$  consists of a map  $p(1) \rightarrow 2$  that assigns to each position in  $p$  whether it belongs to  $p_1$  or  $p_2$ .
- A right-module  $\rho : p \rightarrow p \triangleleft 2y$  consists of a map  $p[i] \rightarrow 2$  for each  $i : p(1)$  that assigns to each direction whether it should go to  $y_1$  or  $y_2$ .

To support  $N$  mutually-inductive types, one can use a bicomodule  $Ny \xleftarrow{\quad} \triangleleft Ny$ . More generally, to support indexed inductive types with a parameter type  $A$ , one can use a bicomodule  $Ay \xleftarrow{\quad} \triangleleft Ay$ .

This development gives a new perspective on “modes”, splitting a type (like  $\mathfrak{t}$ ) into multiple types (like  $\mathfrak{t}1$  and  $\mathfrak{t}2$ ) where each has different characteristics.

**Question 1.** What is the type-theoretic interpretation of endobicomodules when the domain is not a linear  $Ay$ , but rather an arbitrary polynomial  $q$ ?

## 2 Foundations of Poly

What is the essence of **Poly**?

### 2.1 A Zoo of Definitions

There are many equivalent definitions of **Poly**. One could say that **Poly** is:

1. the category of dependent lenses;
2. the coproduct completion of the product completion of the terminal category;
3.  $\mathbf{Fam}(\mathbf{Set}^{\text{op}})$ ;
4. the category of Grothendieck lenses;
5. the category of **Set**-indexed coproducts of representable functors;
6. a diagram in a locally cartesian closed category;
7. the category of connected-limit-preserving functors.

We observe that these definitions seem to be naturally grouped as follows:

- I. Perspectives 1. and 2. describe **Poly** by freely adding limits and then colimits to a category; these look like  $\mathbf{Fam}(\mathbf{Lim}(\mathcal{C})^{\text{op}})$ .

- II. Perspectives 3. to 5. describe **Poly** by freely adding colimits to a category that already has limits; these look like  $\mathbf{Fam}(\mathcal{C}^{\text{op}})$ .
- III. Perspectives 6. and 7. describe **Poly** in terms of structure that already exists in a category.

What structure of **Poly** remains as we vary the parameters on each construction? Group I. is a special case of Group II., but preliminary discussions suggest that freely-added limits are not essential; we therefore focus on Group II.. Here, we always have coproducts, since they are freely added. Moreover, we get Day convolution structures for monoidal structures available in  $\mathcal{C}$ . Recall that the objects of  $\mathbf{Fam}(\mathcal{C}^{\text{op}})$  are pairs  $(A : \mathbf{Set}, B : A \rightarrow \mathcal{C})$  of positions and directions, where the domain of  $B$  is the set  $A$  treated as a discrete category. For any monoidal structure  $(\cdot, I)$  on  $\mathcal{C}$ , we get the monoidal structure

$$(A, B) \odot (A', B') = (A \times A', (a, a') \mapsto B(a) \cdot B'(a'))$$

on  $\mathbf{Fam}(\mathcal{C}^{\text{op}})$ . We can also define the composition product  $\triangleleft$  as in **Poly**, using external hom  $\mathcal{C}(-, =)$  in place of the function space  $\rightarrow$ .

**Question 2.** Defined this way, what properties does  $\triangleleft$  retain?

Perspective 6. generally behaves like **Poly** regardless of the base category and has been studied extensively in the literature. In his lightning talk, Kevin discussed that Perspective 7. can be altered to *finite-connected-limit-preserving* functors to produce a **Poly**-like category.

**Question 3.** What other properties on functors describe categories resembling **Poly**?

## 2.2 Poly as a Friendly Normal Duoidal Category

From another viewpoint, one could argue that **Poly** is fundamentally about the  $\otimes$  and  $\triangleleft$  monoidal structures. Most constructions in **Poly** are defined in terms of adjoints to these structures. Moreover, these monoidal structures  $(y, \otimes)$  and  $(y, \triangleleft)$  are normal duoidal. Preliminary discussions suggest that generalizations of **Poly** may arise through normal duoidal structures, but more work is needed to develop this idea further.